

$$S = (\mathcal{D}, \succeq, Q, \succeq^*, T, V, F)$$

\succeq - preference on document representations

\succeq^* - preference on query representation

(\mathcal{D}, \succeq) – defines the document space

(\mathcal{Q}, \succeq^*) – defines the query space

ALL IN THE CONTEXT OF ONE USER
NEED

Learning in Vector Model using Relevance Feedback

Optimal Query Formulation

$$\underline{q} = (\underline{q}_{1,2} \quad \underline{q}_2 \quad \dots \quad \underline{q}_n)$$

$$\underline{d}_\alpha = (W_{\alpha 1}, W_{\alpha 2}, \dots, W_{\alpha n})$$

choose \underline{q} s.t.

$$\underline{d}_\alpha \underline{q}^T = \begin{cases} > 0, \text{ if } \underline{d}_\alpha \in REL \\ < 0, \text{ if } \underline{d}_\alpha \in NREL \end{cases}$$

for $\alpha = 1, 2, \dots, p$

In the following we apply the “conversion” operation for \underline{d}_α

to get $\hat{\underline{d}}_\alpha$

$$\text{Let } \hat{\underline{d}}_\alpha = \begin{cases} \underline{d}_\alpha, \text{ if } \underline{d}_\alpha \in REL \\ -\underline{d}_\alpha, \text{ if } \underline{d}_\alpha \in NREL \end{cases}$$

$$\hat{W} = \begin{pmatrix} \hat{\underline{d}}_1 \\ \hat{\underline{d}}_2 \\ \bullet \\ \bullet \\ \hat{\underline{d}}_p \end{pmatrix}$$

$$\underline{0} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\hat{W} \underline{q}^T > \underline{0}$$

- Find the best possible \underline{q}
- Relevance feedback

PROBLEM STATEMENT

Find \underline{q} such that
 $J_p(\underline{q})$ is minimized
Subject to

$$\hat{d}_\alpha \underline{q}^T \succ 0$$

for all α

This is a system of linear in equalities

Geometrical PR

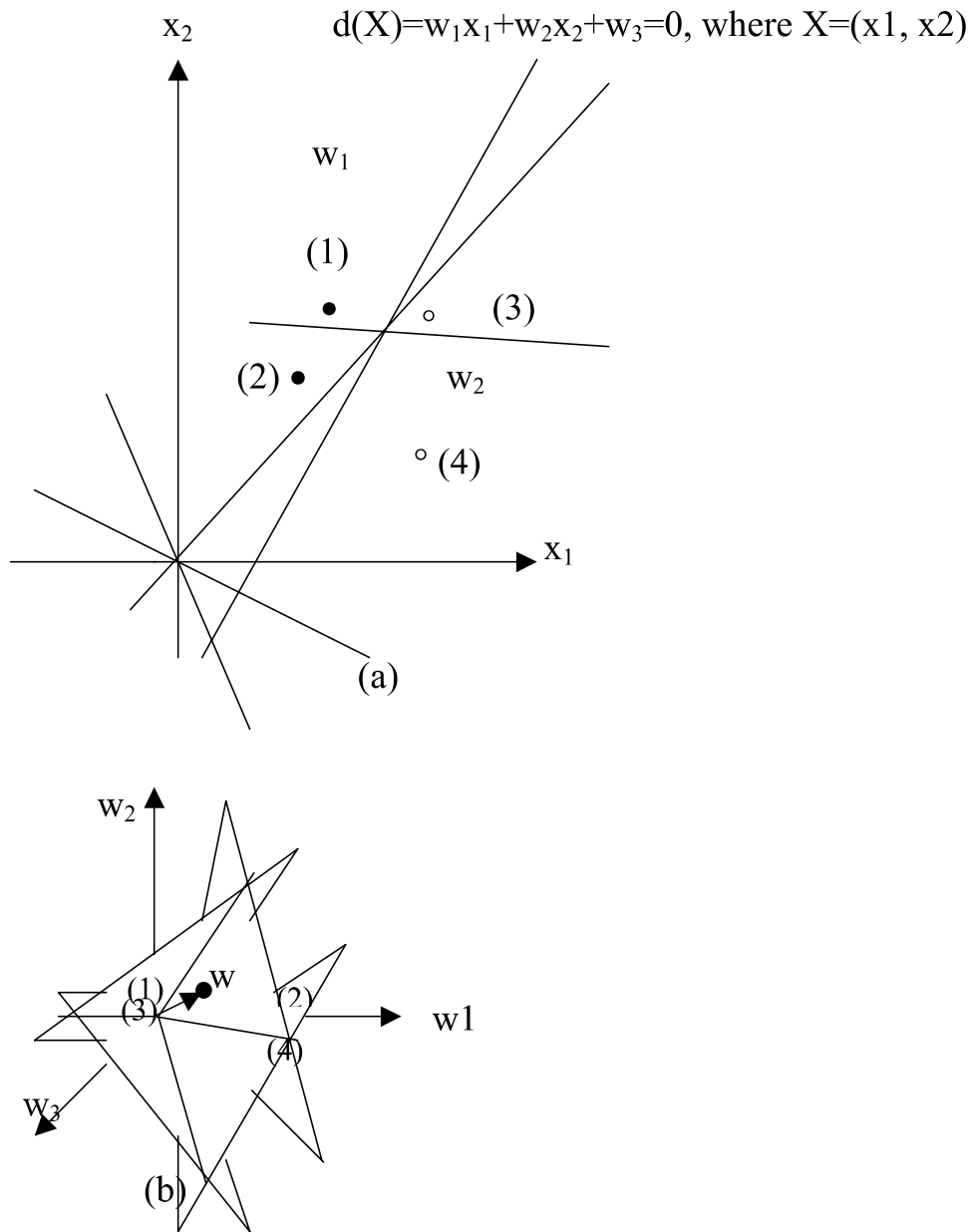
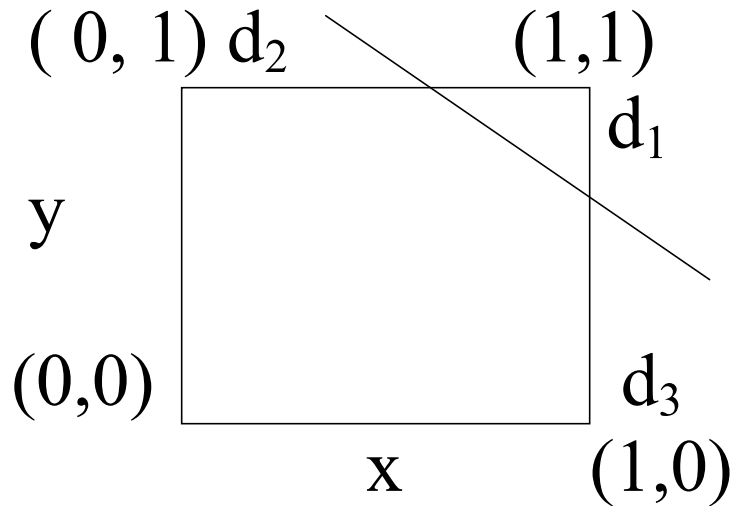


Figure 2.5. Geometrical illustration of the pattern space and the weight space.

(a) Pattern space. (b) Weight space



$(1,1)$	$REL \leftarrow \underline{d}_1$
$(0,1)$	$NREL \leftarrow \underline{d}_2$
$(1,0)$	$NREL \leftarrow \underline{d}_3$
$(0,0)$	$NREL$



$$\hat{d}_1 = (1, 1, 1)$$

$$\hat{d}_2 = (0, -1, -1)$$

$$\hat{d}_3 = (-1, 0, -1)$$

homogeneous
coordinate
representation

ITERATIVE (DESCENT)

PROCEDURES

- Instead of a “batch” approach, here we consider an iterative approach.

$$\underline{q}^{(k+1)} = \underline{q}^{(k)} - \rho_k \frac{\partial J(\underline{q})}{\partial \underline{q}} \Big|_{\underline{q} = \underline{q}^{(k)}}$$

ρ_k – grain factor of step (iteration) k

Many forms of $J(\underline{q})$ are possible.

d_α is misclassified if $\hat{d}_\alpha \underline{q}^T \leq 0$

Let $y(\underline{q}) = \{ \hat{d}_\alpha \mid \hat{d}_\alpha \underline{q}^T \leq 0 \}$

Perception criterion Function

$$J_p(\underline{q}) = - \sum_{\hat{d}_\alpha \in y(\underline{q})} \hat{d}_\alpha \underline{q}^T$$

Taking a derivative of $J_p(\underline{q})$ with respect to \underline{q} yields: $\frac{\partial J_p(\underline{q})}{\partial \underline{q}} = - \sum_{\hat{d}_\alpha \in y(\underline{q})} \hat{d}_\alpha \underline{q}^T$

We, therefore, adjust $\underline{q}^{(k)}$ by $-\sum_{\hat{d}_\alpha \in y(\underline{q}^k)} \hat{d}_\alpha$

$$\underline{q}^{(k+1)} = \underline{q}^{(k)} + \rho_k \sum_{\hat{d}_\alpha \in y(\underline{q}^k)} \hat{d}_\alpha$$

\underline{q}^k is modified w.r.t.
 a set of training
 samples (documents)
 -- learning is by epoch

$$\underline{q}^{(k+1)} = \underline{q}^{(k)} + \rho_k \underline{S}$$

where $\underline{S} = \begin{cases} 0, & \text{if } d_\alpha \text{ is correctly classified} \\ \hat{d}_\alpha, & \text{otherwise} \end{cases}$

-- learning is by sample

$$0 < \rho_k \leq 1$$

PERCEPTRON CRITERION

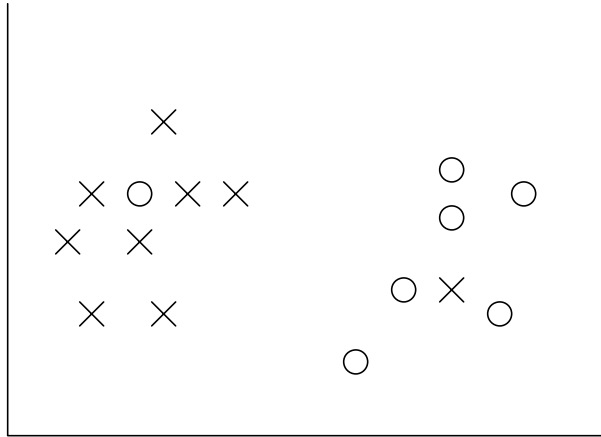
$$J_p(\underline{q}) = \sum_{\hat{d} \in y(\underline{q})} \hat{d} \underline{q}^T$$

where $y(\underline{q})$ is the set of training vectors misclassified by \underline{q}

Training by Epoch PERCEPTRON CONVERGENCE ALGORITHM (PCA)

- (1) $k=0$; Choose initial query vector \underline{q}^0
- (2) Determine $y(\underline{q}^k)$
- (3) If $y(\underline{q}^k) = \phi$, terminate
- (4) $\underline{q}^{k+1} = \underline{q}^k + \rho_k \sum_{\hat{d} \in y(\underline{q}^k)} \hat{d}$
- (5) $k = k+1$, go to step (2)

linearizability



Theorem: PCA will terminate if linearizability property holds for the training data. EX.

$$\underline{d}_1 = (1, 1, 0, 1, 1) \quad \} \text{ NREL}$$

$$\left. \begin{array}{l} \underline{d}_2 = (1, 0, 1, 0, 1) \\ \underline{d}_3 = (0, 1, 1, 0, 1) \end{array} \right\} \text{ REL}$$

$$\underline{d}_4 = (0, 1, 0, 1, 1) \quad \} \text{ NREL}$$

$$\hat{d}_1 = (-1, -1, 0, -1) \quad \text{🗨️}$$

$$\hat{d}_2 = (1, 0, 1, 0, 1)$$

$$\hat{d}_3 = (0, 1, 1, 0, 1)$$

$$\hat{d}_4 = (0, -1, 0, -1) \quad \text{🗨️}$$

$$\underline{q}^0 = (0, 0, 0, 0, 0)$$

$$y(\underline{q}^0) = (\text{all of them})$$

$$\underline{q}^1 = (0, -1, 2, -2, 0)$$

$$\text{let } \rho_k = 1$$

$$y(\underline{q}^1) = \phi$$

$$\underline{q}^{\text{opt}} = (0, -1, 2, -2, 0)$$